

Compressed Sensing Based Methods for Switched Array Imaging

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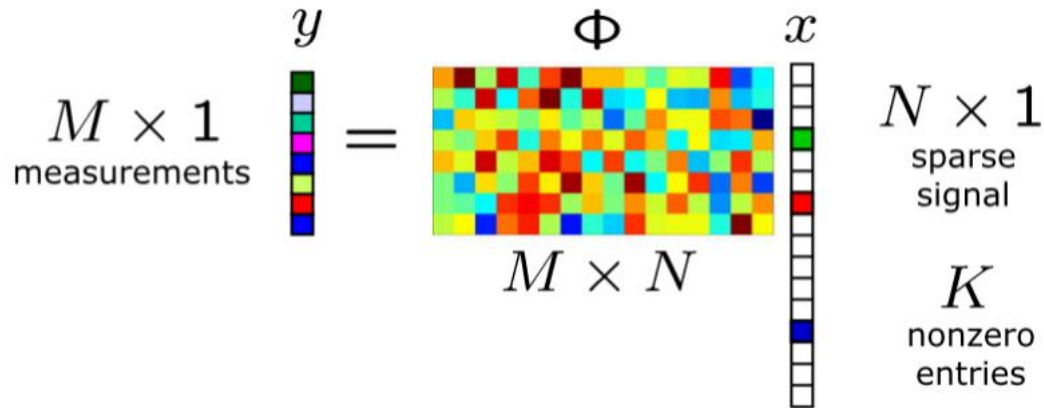
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Outline

1. Compressive sensing (CS) background
2. CS based array imaging
3. Performance analysis
4. Conclusion

Compressive sensing

Linear system



Sensing and compressing

$$y = \Phi x$$

Reconstruction

$$\min_x \|\mathbf{x}\|_0 \quad s.t. \quad y = \Phi x$$

Necessary condition for CS reconstruction:

1. Φ satisfy the RIP or Φ has low mutual coherence.
2. Signal x is sparse or x is compressible in a certain basis.

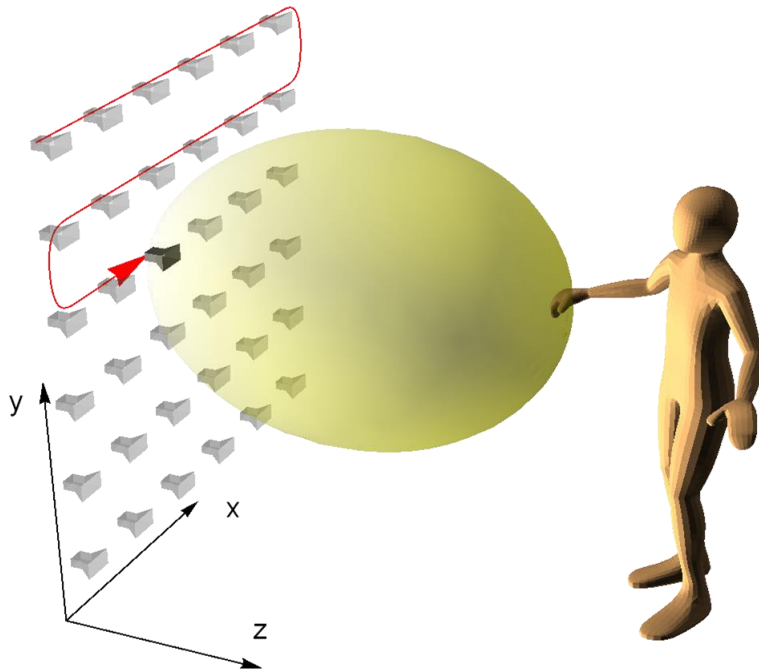
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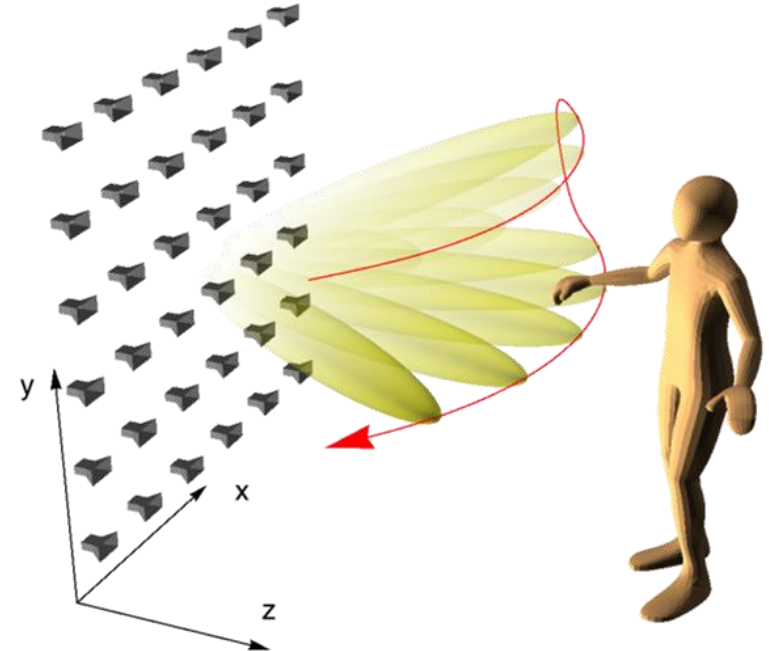
CS based array imaging

Array model

SAR Scheme

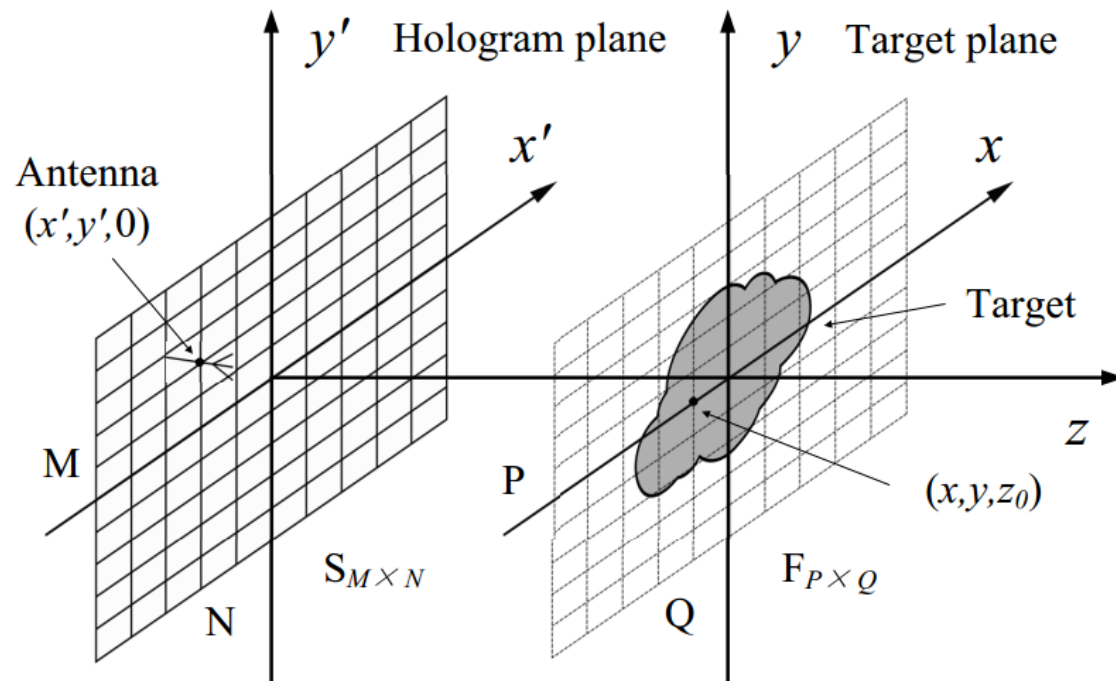


Phased Array Scheme



CS based array imaging

Switched array

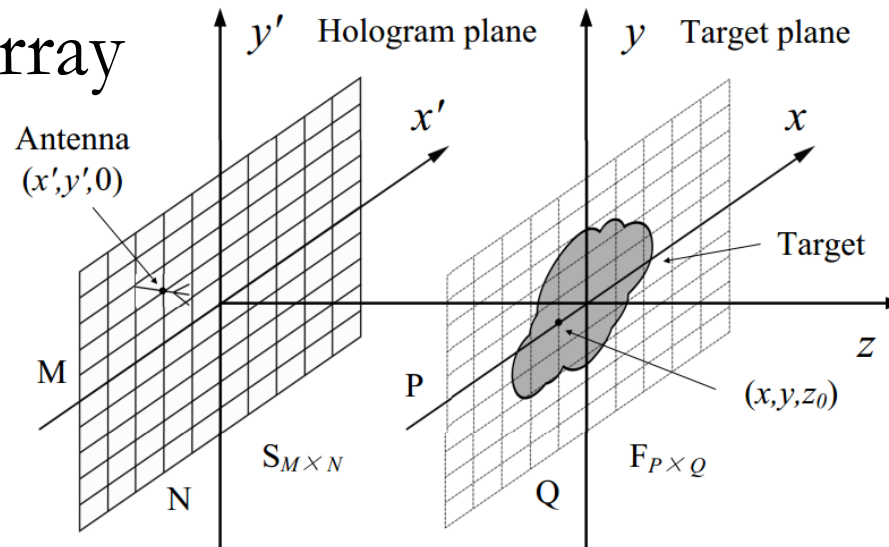


Forward model

$$s(x', y') = \iint f(x, y) \exp(-j2kR) dx dy,$$

CS based array imaging

Switched array



Forward model

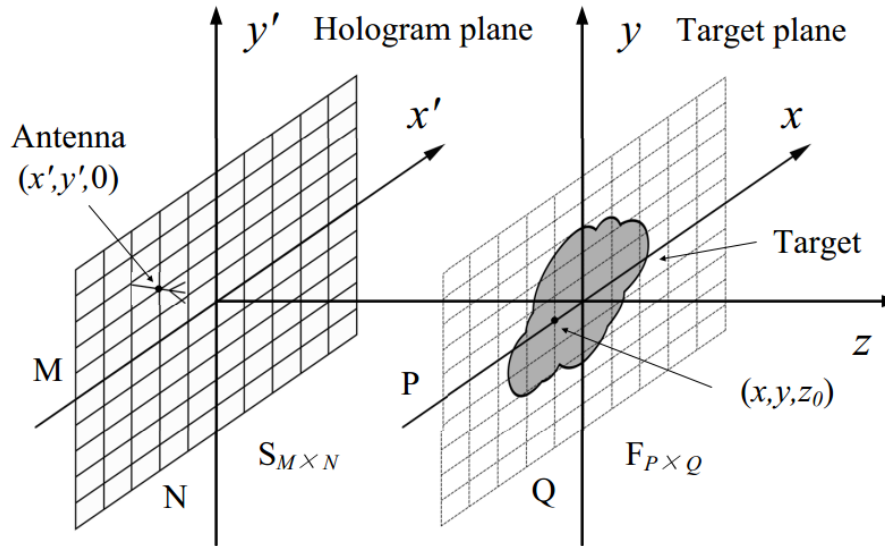
$$\mathbf{S} = \mathbf{H}\mathbf{F}, \quad \mathbf{H} = \mathbf{F}\mathbf{T}_{2D}^{-1}[\mathbf{F}\mathbf{T}_{2D}[\cdot] \exp(jk_z z_0)]$$

FT-CS

Backward model (backpropagation algorithm)

$$\mathbf{F} = \mathbf{H}^\dagger \mathbf{S}, \quad \mathbf{H}^\dagger = \mathbf{F}\mathbf{T}_{2D}^{-1}[\mathbf{F}\mathbf{T}_{2D}[\cdot] \exp(-jk_z z_0)]$$

CS based array imaging



Forward model

$$s(x', y') = \iint f(x, y) \exp(-j2kR) dx dy$$

D-CS

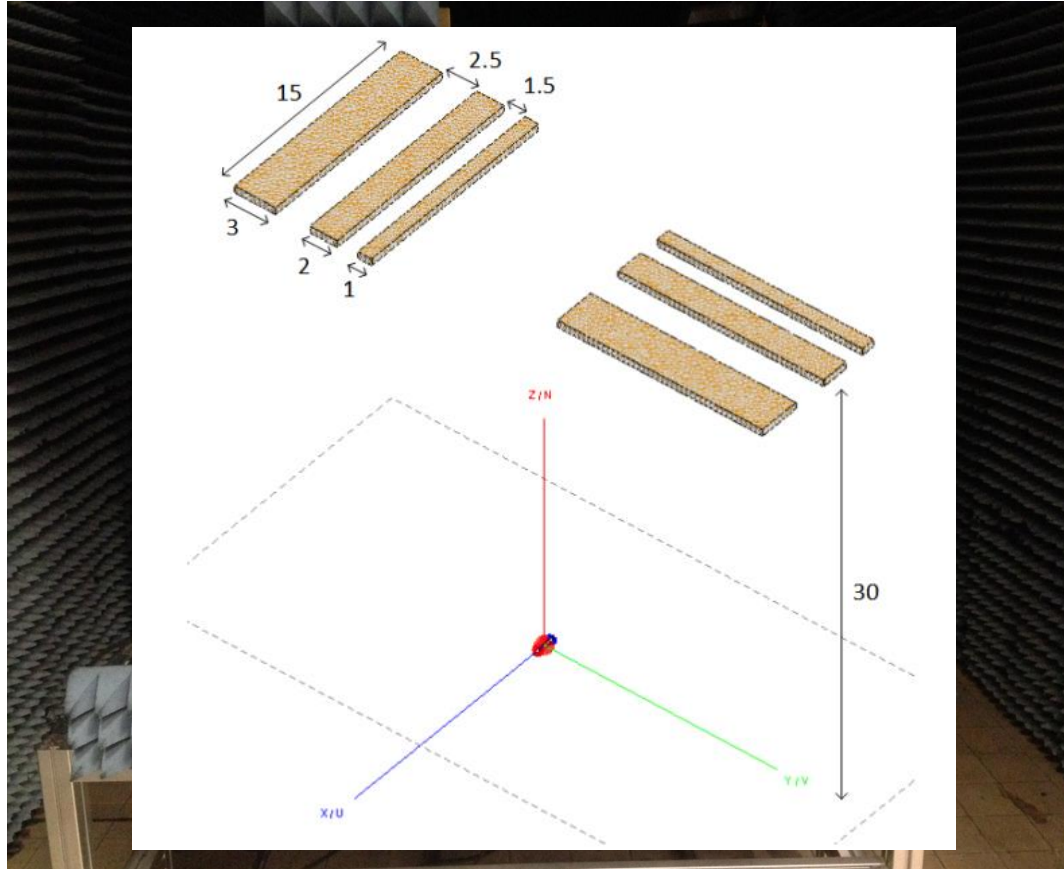
$$\mathbf{s} = \mathbf{A}\mathbf{f} \quad s(m, n) = \sum_{i=1}^P \sum_{j=1}^Q f(i, j) \exp(-j2kR(m, n, i, j))$$

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Performance Analysis

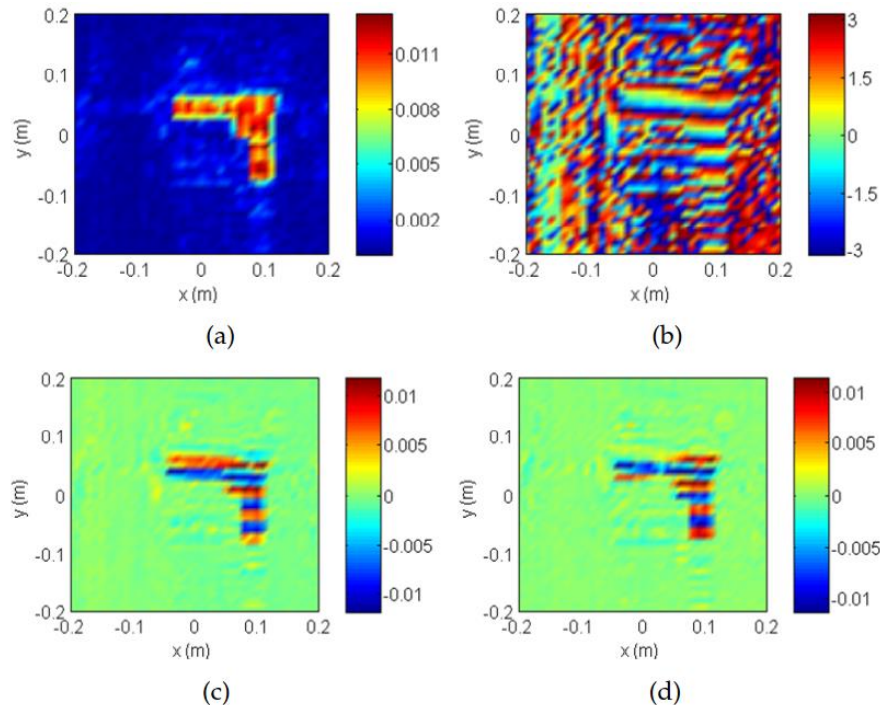
Simulation and experiment



Scanning system

Performance Analysis

Sparsity constraint



$$\hat{f} = \underset{f}{\operatorname{argmin}} \left\| \dot{M} A f - \mathbf{y} \right\|_2 + \alpha [\operatorname{TV}(\mathbf{F}_r) + \operatorname{TV}(\mathbf{F}_i)]$$

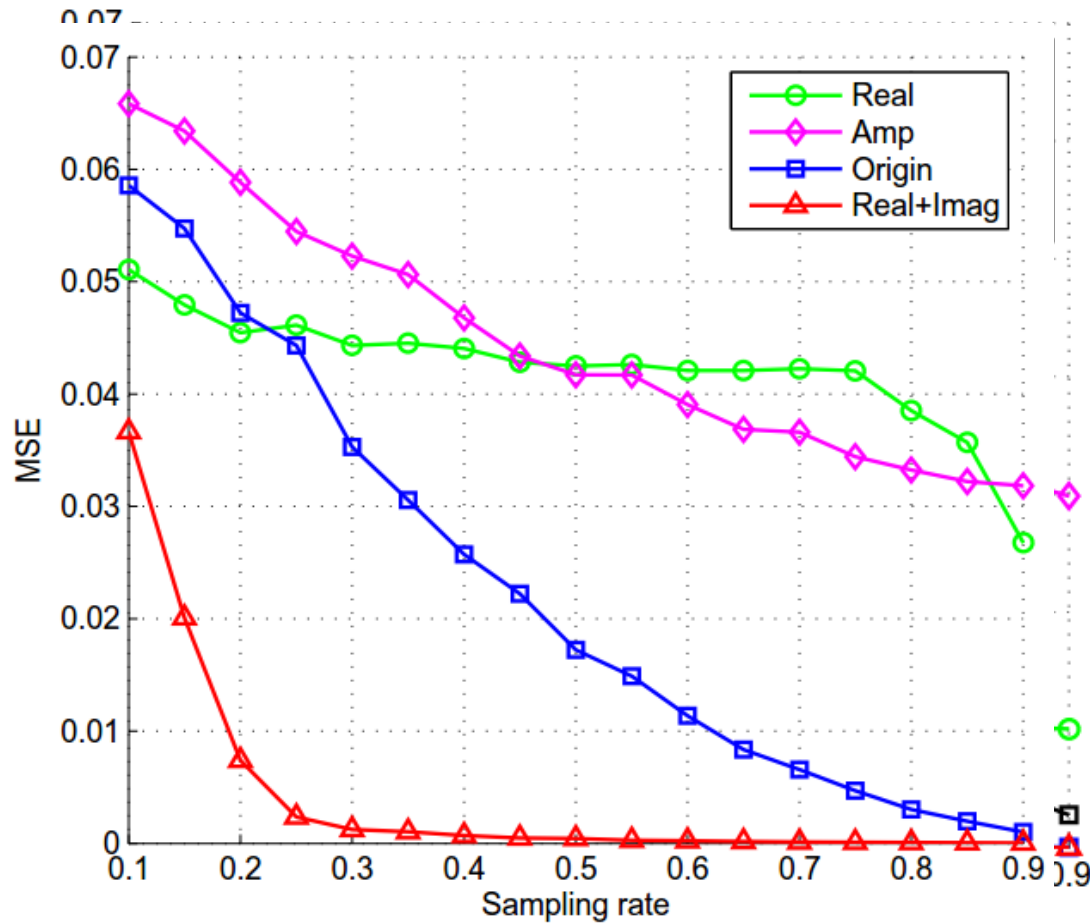
$$\hat{\mathbf{F}} = \underset{\mathbf{F}}{\operatorname{argmin}} \left\| \mathbf{M} \cdot * \mathbf{H} \mathbf{F} - \mathbf{Y} \right\|_2 + \alpha [\operatorname{TV}(\mathbf{F}_r) + \operatorname{TV}(\mathbf{F}_i)]$$

$$\hat{\mathbf{F}} = \underset{\mathbf{F}}{\operatorname{argmin}} \left\| \mathbf{M} \cdot * \mathbf{H} \mathbf{F} - \mathbf{Y} \right\|_2 + \alpha \operatorname{TV}(\mathbf{F})$$

where $\mathbf{F} = \mathbf{F}_r + j\mathbf{F}_i$

Performance Analysis

Sparsity constraint



FT-OS and BP

Performance Analysis

Complexity

Time
complexity

$$\text{D-CS model} \quad \mathcal{O}(KM^2N^2 + KN^2)$$

$$\text{FT-CS model} \quad \mathcal{O}(2M^2 + 4M^2 \log M)$$

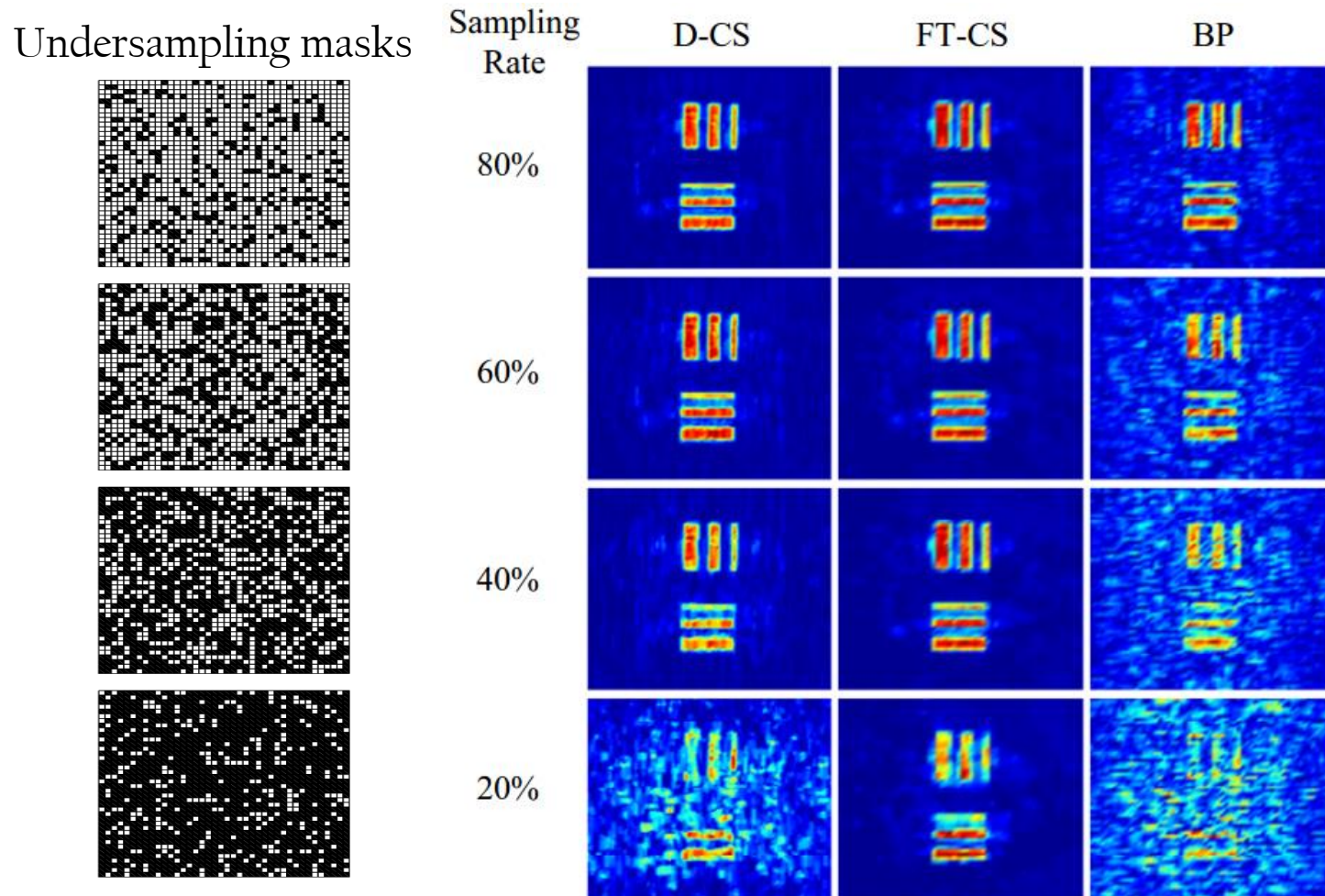
Space
complexity

Table 1. Complexity Comparison of D-CS Methods

Configuration	Computing time (s)	Loading time (s)	Storage
$M = 41, N = 81$	15.03	1.67	72 MB
$M = 41, N = 121$	33.61	3.84	221 MB
$M = 81, N = 121$	140.67	17.28	1.04 MB
$M = 81, N = 161$	224.36	27.12	1.37 GB
$M = 134, N = 134$	1.45×10^3	88.65	2.94 GB
$M = 134, N = 178$	4.58×10^3	717.72	8.23 GB

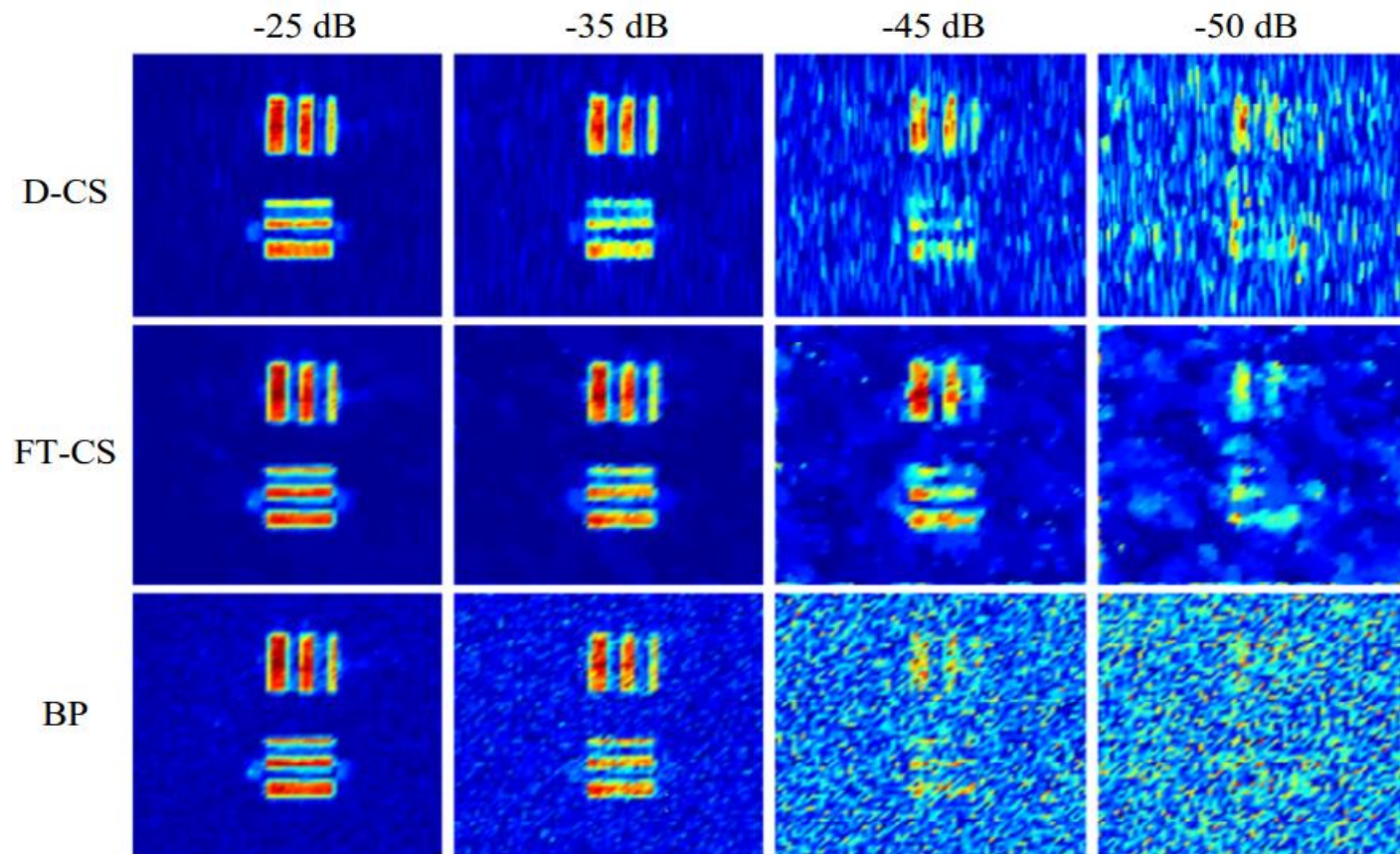
Performance Analysis

Effects of undersampling



Performance Analysis

Effects of background noise



100% sampling rate

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Conclusion

- ❖ Sparsity constraint plays an important role in reconstruction.
- ❖ The D-CS method achieves the best resolution but requires heavy computation and large number of measurements.
- ❖ The FT-CS method does not show much improvement in resolving power. However, it is more robust in many cases.
- ❖ Practical imaging systems are suggested to use the D-CS and FT-CS methods jointly.

Thanks