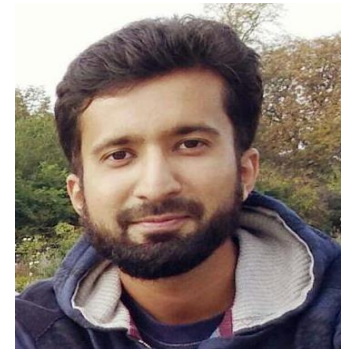
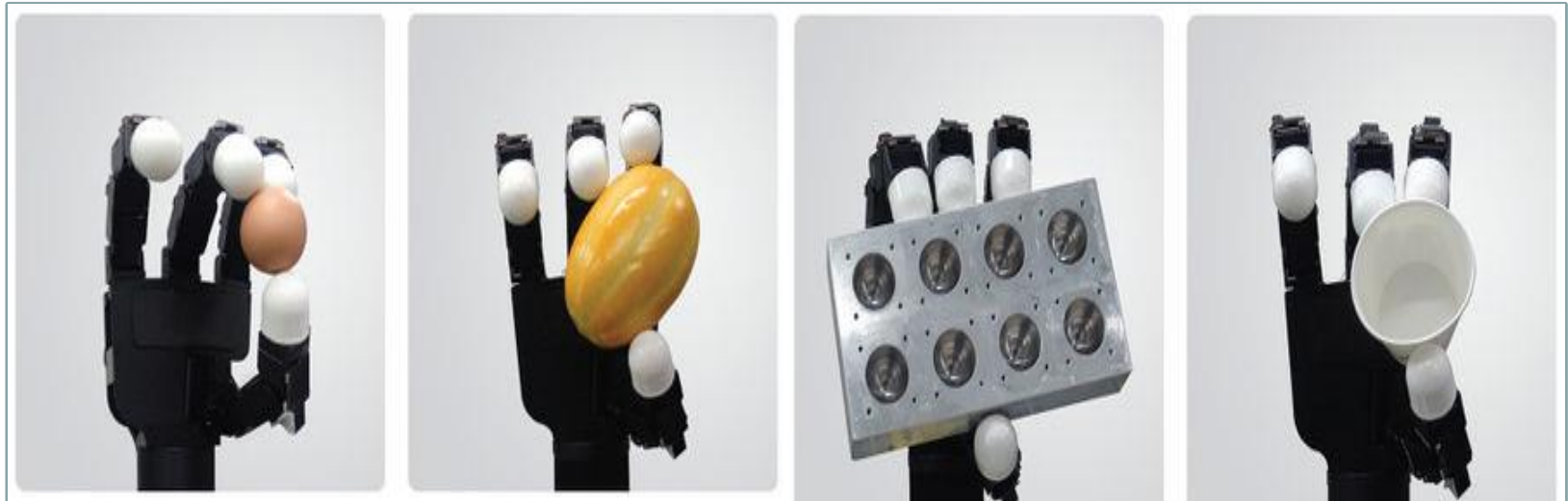


Combining 3D computer vision and haptics for intelligent robotic manipulation

Muhammad Sami Siddiqui



- Recognizing unknown objects from a clutter environment
- Developing an efficient technique for a stable grasping
- Using Multi-Fingered Allegro Hand gripper.



http://wiki.wonikrobotics.com/AllegroHandWiki/index.php/Allegro_Hand_Overview