

Video semantic clustering with sparse and incomplete tags

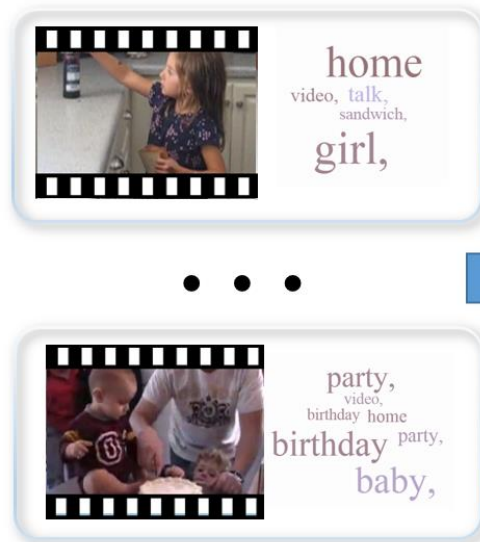
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Introduction

Visual Information + Textual Information

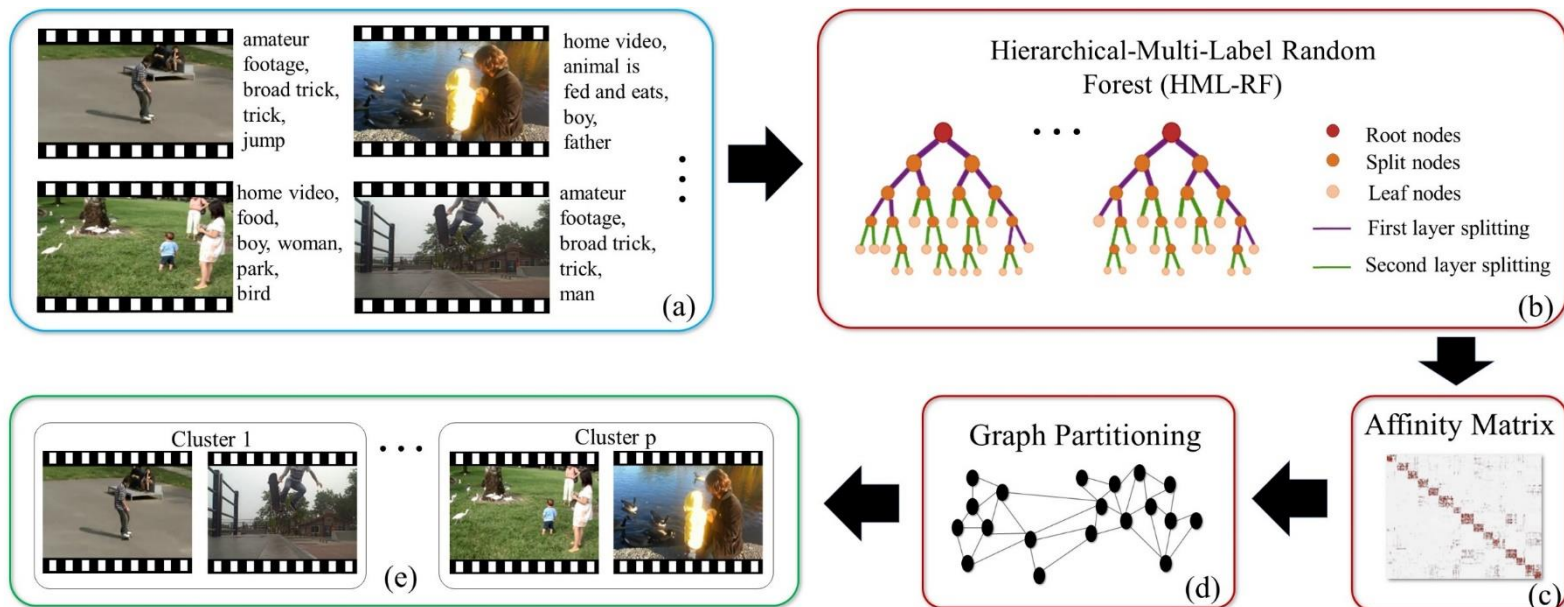


Difficulty:

- Visual and textual data significantly differ in representation and distribution
- Visual features: ambiguous and unreliable
- Tag: inherently sparse and incomplete

- Existing methods
 - Tags are organised and used in a flat structure
 - Tag statistical correlations are not fully exploited
- Contributions
 - A novel tag-based video clustering method capable of effectively fusing information from ambiguous visual features and sparse textual tags
 - A unified tag correlation based algorithm to cope with tag sparseness/incompleteness

Methods



➤ Limitations of existing random forests

✗ Conventional clustering forest:

- (a) fully concatenated representation
- (b) two modalities are not balanced

✗ Conventional classification forest:

- (a) supervised

➤ Merits of the proposed HML-RF model

- ✓ A hybrid model of classification and clustering forests
- ✓ Jointly exploiting heterogeneous visual and tag data
- ✓ Integrating abstract-to-specific tag topology
- ✓ Handling tag sparseness and incompleteness

➤ Hierarchical-Multi-Label Random Forest (HML-RF)

$$\Delta\psi_{sl} = \psi_s - \frac{|L|}{|S|}\psi_l - \frac{|R|}{|S|}\psi_r,$$

Conventional individual
information gain

where L and R denote the data set routed into the left l and right r children,
The uncertainty ψ over the tag distribution was computed as Gini impurity



$$\Delta\psi_{ml} = \sum_{i=1}^m \Delta\psi_{sl}^i$$

Multi-tags information gain

where $\Delta\psi_{sl}^i$ is individual information gain computed in the i -th tag.



$$\Delta\psi_{hml} = \sum_{k=1}^{\mu} \left(\prod_{j=1}^{k-1} (1 - \alpha_j) \alpha_k \sum_{i \in Z_k} \Delta\psi_{sl}^i \right)$$

Adaptive hierarchical multi-
label information gain

where Z_k denotes the tag index set of the k -th layer in the tag hierarchy (totally μ layers), with $\cup_{k=1}^{\mu} Z_k = Z$, and $\forall_{j \neq k} Z_j \cap Z_k = \emptyset$. Binary flag $\alpha_k \in \{0, 1\}$ indicates the impurity of the k -th tag layer, $k \in \{1, \dots, \mu\}$, i.e. $\alpha_k = 0$ when tag values are identical/pure across all the training samples S of split node s in any tag $i \in Z_k$, $\alpha_k = 1$ otherwise. The target layer is k in case that $\alpha_k = 1$ and $\forall \alpha_j = 0, 0 < j < k$.

➤ Handling tag sparseness and incompleteness

Idea: Estimate soft tag labels (real valued) with two tag statistical correlations mined from available tag data

(I) Co-occurrence $\varrho_{i,j} = co_{i,j}/o_j$,

where $co_{i,j}$ denotes the co-occurrence frequency of tags i and j . o_j denotes the number of occurrences of tag j over all samples.

once $\varrho_{i,j}$ is obtained, for a potentially missing tag $i \in Z_k$ of $\mathbf{x} \in S_{\text{miss}}$, we estimate its positive score $\hat{y}_{\cdot,i}^+$ via:

$$\hat{y}_{\cdot,i}^+ = \sum_{j \in \{Z_{k+1}, \dots, Z_{\mu}\}} \varrho_{i,j} y_{\cdot,j}$$

where $y_{\cdot,j}$ refers to the j -th tag value of \mathbf{x} .

(II) Mutual-exclusion $\epsilon_{i,j} = \max(0, r_{i,j}^{-+} - r_i^-)/(1 - r_i^-)$,

where r_i^- refers to negative sample percentage on tag i across all samples, and $r_{i,j}^{-+}$ negative sample percentage on tag i over samples with positive tag j .

we predict the negative score $\hat{y}_{\cdot,i}^-$ for \mathbf{x} on tag i with:

$$\hat{y}_{\cdot,i}^- = \sum_{j \in \{Z_{k+1}, \dots, Z_{\mu}\}} \epsilon_{i,j} y_{\cdot,j},$$

Evaluations

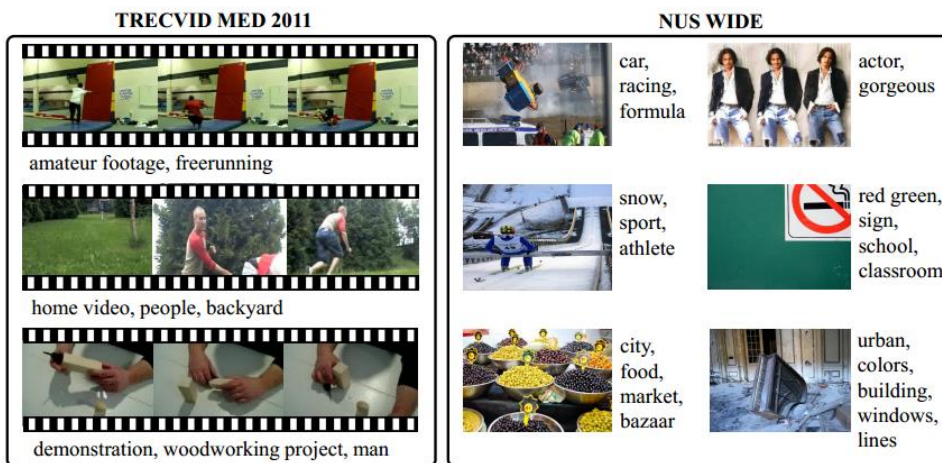


Figure 3: Examples from the TRECVID MED 2011 [56] and NUS-WIDE [9] dataset.

Table 1: Comparing clustering methods on TRECVID MED 2011 [56].

Input mode	Method	Purity	NMI	RI	F1	ARI
ViFeat	K-means[2]	0.26	0.19	0.88	0.14	0.08
	SpClust[14]	0.25	0.20	0.88	0.15	0.07
	ClustRF[48]	0.23	0.17	0.87	0.14	0.08
	AffProp[62]	0.23	0.16	0.87	0.14	0.07
	MMC[63]	0.25	0.19	0.88	0.14	0.09
BiTag	K-means[2]	0.51	0.52	0.86	0.30	0.23
	SpClust[14]	0.71	0.73	0.93	0.56	0.60
	ClustRF[48]	0.77	0.81	0.94	0.64	0.60
	AffProp[62]	0.50	0.44	0.87	0.28	0.21
	MMC[63]	0.76	0.72	0.95	0.64	0.60
DetScore	K-means[2]	0.63	0.60	0.93	0.50	-
	SpClust[14]	0.82	0.76	0.96	0.69	-
	MMC[63]	0.83	0.78	0.96	0.73	-
	L-MMC[3]	0.86	0.82	0.97	0.79	-
ViFeat&BiTag-cmb	K-means[2]	0.51	0.49	0.90	0.34	0.24
	SpClust-cmb[14]	0.76	0.74	0.94	0.62	0.66
	ClustRF[48]	0.23	0.17	0.87	0.15	0.08
	AffProp[62]	0.51	0.46	0.86	0.29	0.21
ViFeat&BiTag-bl	SpClust-bl[14]	0.75	0.72	0.95	0.62	0.59
	CCA+SpClust[19]	0.85	0.81	0.97	0.77	0.75
	3VCCA+SpClust[21]	0.86	0.86	0.97	0.78	0.77
	CC-Forest[47]	0.41	0.33	0.89	0.41	0.19
	AASC[13]	0.30	0.15	0.87	0.13	0.06
	MMC[63]	0.79	0.72	0.95	0.66	0.66
	DCCA[24]	0.84	0.80	0.96	0.74	0.72
	DCCAE[25]	0.84	0.80	0.97	0.75	0.73
	S-MMC[4]	0.87	0.84	0.97	0.79	-
	F-MMC[4]	0.90	0.88	0.98	0.84	-
	HML-RF(Ours)	0.94	0.90	0.98	0.88	0.87

Evaluations

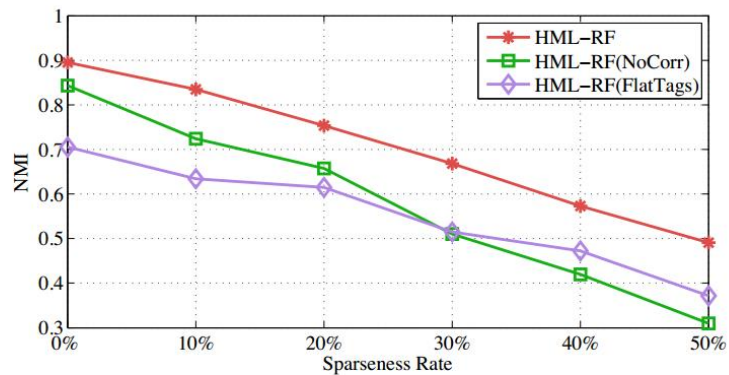


Figure 7: Evaluating the effectiveness of specific HML-RF components on TRECVID MED 2011 [56].

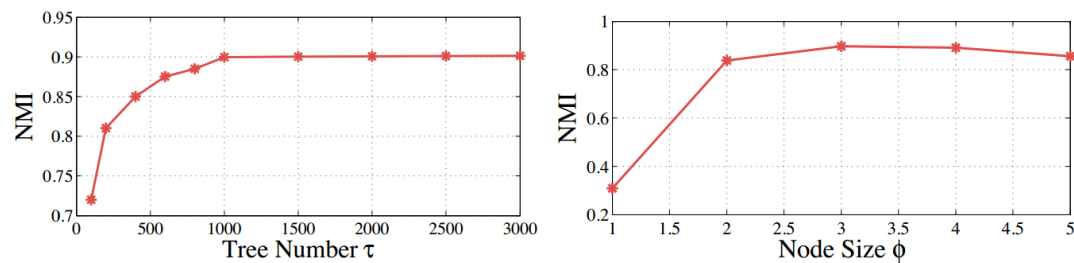
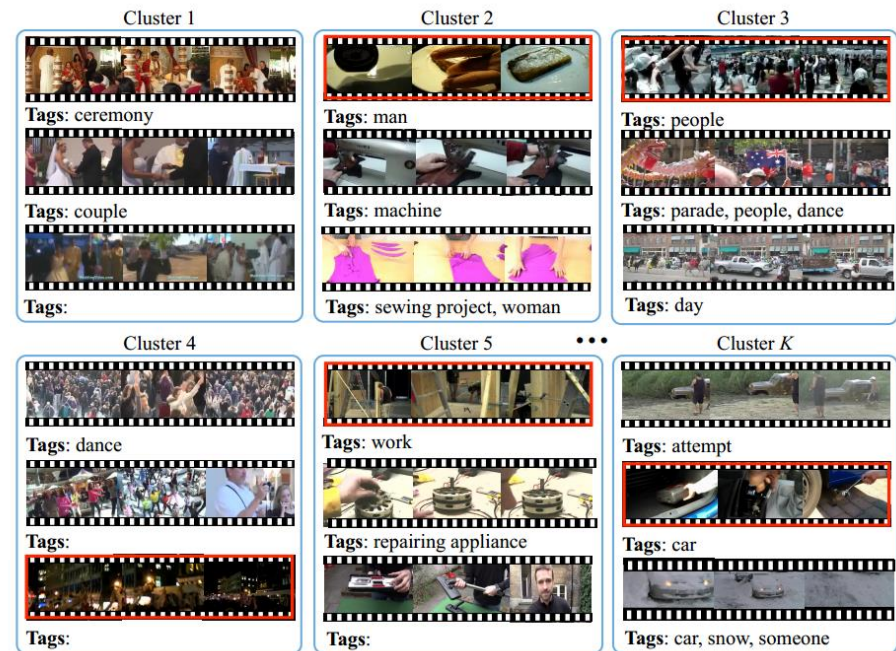


Figure 8: Clustering performance in NMI of HML-RF over different forest sizes (τ) and node size (ϕ) on TRECVID MED 2011 [56].

Thank you