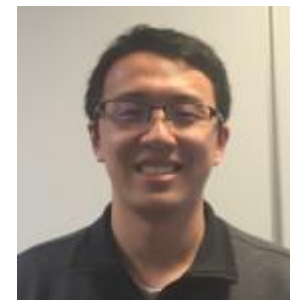


Multi Task Learning for Robotics Control

Chenyang Zhao



- Learning individual tasks by behavior exploration
- Restructuring Knowledge Base from learned tasks
- Accelerate learning process for new tasks by applying Knowledge Base

